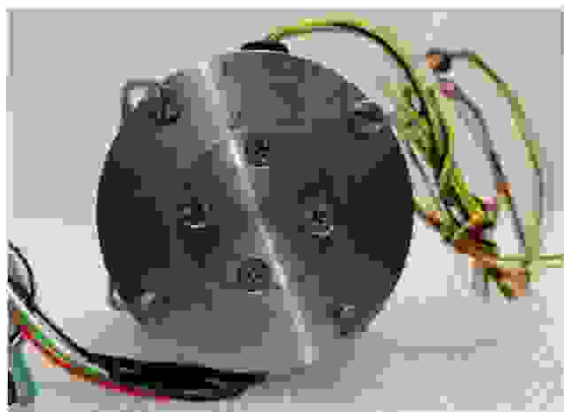


50 系列(Series)-J50BH002 混合式步进电机(Hybrid Stepper Motor)



主要技术参数 Main technical parameters

引出线形式 Lead wire connection type

驱动方式 Drive mode

工作制 Working system

步距角 Step angle

额定电压 Rated voltage/V D.C

保持转矩 Holding torque/N·m

自定位转矩 Detent torque/N·m

步距角误差 Step angle error

相电阻 Phase resistance/ Ω

相电感 Phase inductance/mH

牵出力矩 Pullout torque/N·m

重量 Weight/kg

两相 6 线 Two Phase 6-line

双极恒流/双四拍驱动 Bipolar constant current/

double four beat drive

真空长时 Long term vacuum

1.8°

24

≥ 0.75 @ A & B 通 (Electrify) A

≤ 0.035

$\pm 5\%$

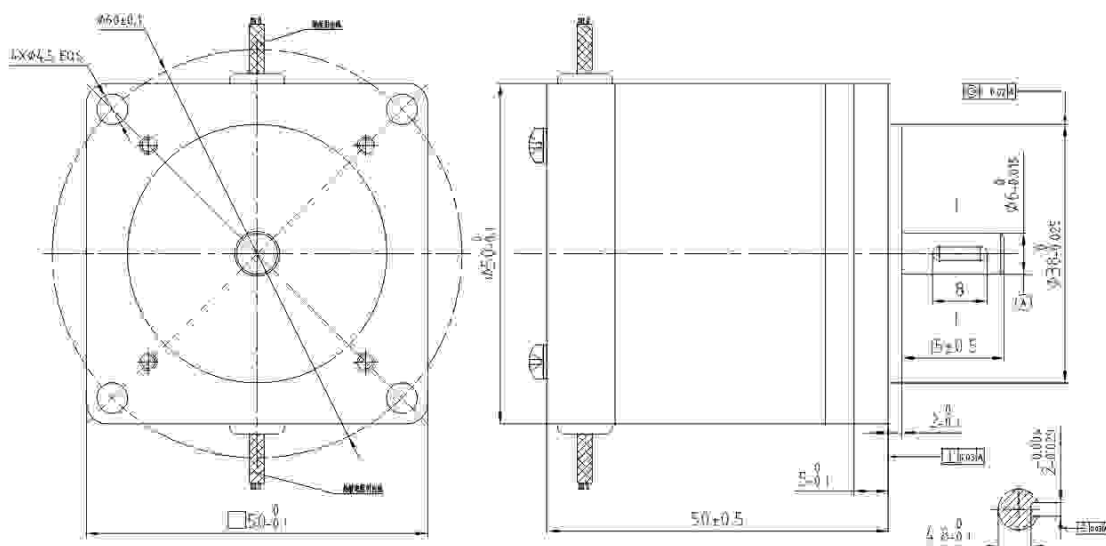
$4.7 \times (1 \pm 10\%)$

$20 \times (1 \pm 25\%)$

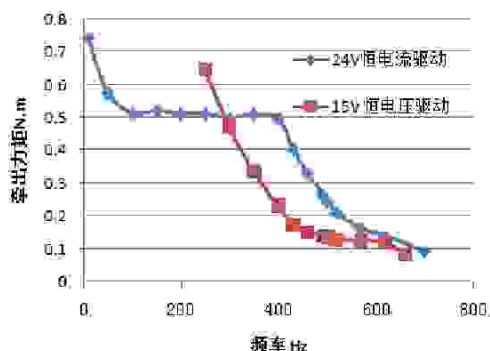
$\geq 0.2 @ 500 \text{ Hz}$

≤ 0.6

外形图(Outline Drawing)/mm

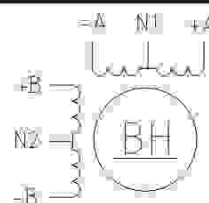


其他补充(Other Supplements)



牵出力矩频率特性(Pullout torque frequency characteristics)

电路图(Circuit Diagram)



引出线定义	A 相正	A 相负	A 相中点	B 相正	B 相负	B 相中点
Definition of lead wire	A-phase positive	A-phase negative	A-phase midpoint	B-phase positive	B-phase negative	B-phase midpoint

引出线标识	A+	A-	N1	B+	B-	N2
Identification of lead wire	A+	A-	N1	B+	B-	N2